### On the Vlasov Inverse problem and the Continuum Hamiltonian Hopf Bifurcation

P. J. Morrison

Department of Physics and Institute for Fusion Studies The University of Texas at Austin

morrison@physics.utexas.edu
http://www.ph.utexas.edu/~morrison/

Vlasovia, Copanello 2016

Collaborators: D. Pfirsch, B. Shadwick, G. Hagstrom, ....

Goal: Describe the <u>integral transform</u> that diagonalizes continuous spectrum, and some of its uses: Solve Landau problem. Define signature for continuous spectrum. Motivates a Kreinlike theorem for instabilities that emerge from the continuous spectrum. Motivates a nonlinear normal form (pde).

<u>Overview</u>

- Integral Transform and Inverse Problem
- Energy and Signature
- Continuum Hamiltonian Hopf Bifurcation
- Nonlinear Normal Forms Single Wave Model, Hickernell-Berk-Breizman equation, ...

# • Integral Transform and Inverse Problem

# **Integral Transforms**

Fourier:

$$f(x) \longleftrightarrow g(k)$$

$$f(x) = \int_{\mathbb{R}} K(x,k)g(k) \, dk \quad \text{where} \quad K(x,k) = e^{ik \cdot x}$$

Hilbert:

$$f(v) \longleftrightarrow g(u)$$
  
 $f(v) = \int_{\mathbb{R}} K(u,v)g(u) \, du$  where  $K(u,v) = \frac{\mathbb{P}}{\pi u - v}$ 

### **A** General Transform for Continuous Spectra

Definition:

$$f(v) = G[g](v) := A(v) g(v) + B(v) H[g](v) = \int_{\mathbb{R}} K(u, v) g(u) du$$

where A(v) and B(v) are real valued functions of a real variable (K generalized function) such that:

$$B(v) = 1 + H[A](v),$$

and the Hilbert transform

$$H[g](v) := \frac{1}{\pi} \oint \frac{g(u)}{u-v} du,$$

with  $\oint$  denoting Cauchy principal value of  $\int_{\mathbb{R}}$ .

Actually subset of more general transform!

#### **Transform Theorems**

**Theorem (G1).**  $G: L^p(\mathbb{R}) \to L^p(\mathbb{R}), 1 , is a bounded linear operator:$ 

$$||G[g]||_p \le C_p ||g||_p$$
,

where  $C_p$  depends only on p.

**Theorem (G2).** If A is a good function, then G[g] has an inverse,

$$G^{-1}: L^p(\mathbb{R}) \to L^p(\mathbb{R}),$$

for 1/p + 1/q < 1, given by

$$g(u) = G^{-1}[f](u)$$
  
:=  $\frac{B(u)}{A^2 + B^2} f(u) - \frac{A(u)}{A^2 + B^2} H[f](u),$ 

#### **Vlasov-Poisson System**

Phase space density (1 + 1 + 1 field theory):  $f: \mathbb{T} \times \mathbb{R}^2 \to \mathbb{R}^+, \qquad f(x, v, t) \ge 0$ 

Conservation of phase space density:

$$\frac{\partial f}{\partial t} + v \frac{\partial f}{\partial x} + \frac{e}{m} \frac{\partial \phi[x, t; f]}{\partial x} \frac{\partial f}{\partial v} = 0$$

Poisson's equation:

$$\phi_{xx} = 4\pi \left[ e \int_{\mathbb{R}} f(x, v, t) \, dv - \rho_B \right]$$

Energy:

$$H = \frac{m}{2} \int_{\mathbb{T}} \int_{\mathbb{R}} v^2 f \, dx \, dv + \frac{1}{8\pi} \int_{\mathbb{T}} (\phi_x)^2 \, dx$$

#### Linear Vlasov-Poisson System

Expand about <u>Stable</u> Homogeneous Equilibrium:

$$f = f_0(v) + \delta f(x, v, t)$$

Linearized EOM:

$$\frac{\partial \delta f}{\partial t} + v \frac{\partial \delta f}{\partial x} + \frac{e}{m} \frac{\partial \delta \phi[x, t; \delta f]}{\partial x} \frac{\partial f_0}{\partial v} = 0$$
$$\delta \phi_{xx} = 4\pi e \int_{\mathbb{R}} \delta f(x, v, t) \, dv$$

Linearized Energy (Kruskal-Oberman 1958):

$$H_L = -\frac{m}{2} \int_{\mathbb{T}} \int_{\mathbb{R}} \frac{v \, (\delta f)^2}{f'_0} \, dv \, dx + \frac{1}{8\pi} \int_{\mathbb{T}} (\delta \phi_x)^2 \, dx$$

#### Landau's Problem

Assume

$$\delta f = \sum_{k} f_k(v,t) e^{ikx}, \qquad \delta \phi = \sum_{k} \phi_k(t) e^{ikx}$$

Linearized EOM:

$$\frac{\partial f_k}{\partial t} + ikvf_k + ik\phi_k \frac{e}{m} \frac{\partial f_0}{\partial v} = 0, \qquad k^2 \phi_k = -4\pi e \int_{\mathbb{R}} f_k(v,t) \, dv$$

Three methods:

- 1. Laplace Transforms (Landau 1946)
- 2. Normal Modes (van Kampen 1955)
- 3. Coordinate Change  $\iff$  Integral Transform (PJM, Pfirsch, Shadwick, ... 1992, 2000, ...)

#### **Transform Choice and Identities**

Tailor Transform as follows:

$$A(v) := \epsilon_I(v) = -\pi \frac{\omega_p^2}{k^2} \frac{\partial f_0(v)}{\partial v} \quad \Rightarrow \quad B(v) := \epsilon_R(v) = 1 + H[\epsilon_I](v) \,,$$

General identities written out for this case

•  $G^{-1}$  is the inverse of G

• 
$$G^{-1}[vf](u) = u G^{-1}[f](u) - \frac{\epsilon_I}{|\epsilon|^2} \frac{1}{\pi} \int_{\mathbb{R}} f dv$$

• 
$$G^{-1}[\epsilon_I](u) = \frac{\epsilon_I(u)}{|\epsilon|^2(u)}$$

where  $|\epsilon|^2 = \epsilon_I^2 + \epsilon_R^2$  and recall  $\epsilon_I \sim f'_0$ .

#### **Inverse Proof**

That  $G^{-1}$  is the inverse follows upon calculating  $g = G^{-1}[G[g]]$ , and using Hilbert transform identities:

$$\begin{split} g(u) &= \widehat{G}[f](u) = \frac{\epsilon_R(u)}{|\epsilon(u)|^2} f(u) - \frac{\epsilon_I(u)}{|\epsilon(u)|^2} H[f](u) \\ &= \frac{\epsilon_R(u)}{|\epsilon(u)|^2} \left[ \epsilon_R(u) g(u) + \epsilon_I(u) H[g](u) \right] - \frac{\epsilon_I(u)}{|\epsilon(u)|^2} H\left[ \epsilon_R(u') g(u') + \epsilon_I(u') H[g](u') \right] (u) \\ &= \frac{\epsilon_R^2(u)}{|\epsilon(u)|^2} g(u) + \frac{\epsilon_R(u)\epsilon_I(u)}{|\epsilon(u)|^2} H[g](u) - \frac{\epsilon_I(u)}{|\epsilon(u)|^2} H[g](u) - \frac{\epsilon_I(u)}{|\epsilon(u)|^2} H[H[\epsilon_I] g + \epsilon_I H[g]] (u) \\ &= \frac{\epsilon_R^2(u)}{|\epsilon(u)|^2} g(u) + \frac{\epsilon_R(u)\epsilon_I(u)}{|\epsilon(u)|^2} H[g](u) - \frac{\epsilon_I(u)}{|\epsilon(u)|^2} H[g](u) - \frac{\epsilon_I(u)}{|\epsilon(u)|^2} H[g](u) - \frac{e_I(u)}{|\epsilon(u)|^2} H[e_I](u) H[g](u) - g(u) \epsilon_I(u)] \\ &= g(u) + \frac{\epsilon_R(u)\epsilon_I(u)}{|\epsilon(u)|^2} H[g] - \frac{\epsilon_I(u)}{|\epsilon(u)|^2} H[g] - \frac{\epsilon_I(u)}{|\epsilon(u)|^2} H[e_I] H[g] \\ &= g(u) + \frac{\epsilon_R(u)\epsilon_I(u)}{|\epsilon(u)|^2} H[g](u) - \frac{\epsilon_I(u)}{|\epsilon(u)|^2} H[g](u) [1 + H[\epsilon_I](u)] \\ &= g(u) + \frac{\epsilon_R(u)\epsilon_I(u)}{|\epsilon(u)|^2} H[g](u) - \frac{\epsilon_I(u)}{|\epsilon(u)|^2} H[g](u) \epsilon_R(u) = g(u) \end{split}$$

## **Solution**

Solve like Fourier transforms: operate on EOM with  $G^{-1} \Rightarrow$ ,

$$\frac{\partial g_k}{\partial t} + iku g_k - ik \frac{\epsilon_I}{|\epsilon|^2} \frac{1}{\pi} \int_{\mathbb{R}} f \, dv + ik \frac{\epsilon_I}{|\epsilon|^2} \frac{1}{\pi} \int_{\mathbb{R}} f \, dv = 0$$

$$\frac{\partial g_k}{\partial t} + iku \, g_k = 0$$

and so

$$g_k(u,t) = \mathring{g}_k(u)e^{-ikut}$$

Using  $\mathring{g}_k = G^{-1}[\mathring{f}_k]$  we obtain the solution  $f_k(v,t) = G[g_k(u,t)]$  $= G\left[\mathring{g}_k(u)e^{-ikut}\right] = G\left[G^{-1}[\mathring{f}_k]e^{-ikut}\right]$ 

Equivalant to van Kampen's and Landau's solution!

## **Inverse Problem?**

What is  $g_k(u,t)$  physically? The van Kampen mode electric field!

Sum over modes

where

$$E_k(t) = \int_{\mathbb{R}} \mathring{g}_k(u) e^{-ikut} du = \int_{\mathbb{R}} E_k(\omega) e^{-i\omega t} d\omega$$
$$E_k(\omega) = \mathring{g}_k(u)/|k|.$$

<u>Usual Logic</u>: Choose  $\overset{\circ}{f}_k \to \overset{\circ}{g}_k$  such that

$$\lim_{t\to\infty}E_k(t)\sim e^{-\gamma_L t}$$

Why? Riemann-Lebesgue Lemma:  $\gamma$  determined by closest pole to real axis when  $\mathring{g}_k(u)$  continued into complex *u*-plane.

<u>Inverse Logic</u>: Choose  $E_k(t) \rightarrow \mathring{g}_k \rightarrow \mathring{f}_k$ . Note,  $E_k(t)$  can have ANY  $t \rightarrow \infty$  asymptotic behavior. Price paid is strange  $\mathring{f}_k$ . (special case due to Weitzner 1960s).

# • Energy and Signature

## **Charged Particle on Slick Mountain**



Falls and Rotates  $\Rightarrow$  Precession

Realized in a uniformly charged column.

### **Charged Particle on Quadratic Mountain**

Simple model of FLR stabilization  $\rightarrow$  plasma mirror machine.

Lagrangian:

$$L = \frac{m}{2} \left( \dot{x}^2 + \dot{y}^2 \right) + \frac{eB}{2} \left( \dot{y}x - \dot{x}y \right) + \frac{K}{2} \left( x^2 + y^2 \right)$$

Hamiltonian:

$$H = \frac{m}{2} \left( p_x^2 + p_y^2 \right) + \omega_L \left( y p_x - x p_y \right) - \frac{m}{2} \left( \omega_L^2 - \omega_0^2 \right) \left( x^2 + y^2 \right)$$

Two frequencies:

$$\omega_L = rac{eB}{2m}$$
 and  $\omega_0 = \sqrt{rac{K}{m}}$ 

# Hamiltonian Hopf Bifurcation (Krein Crash)





$$x, y \sim e^{i\omega t} = e^{\lambda t}$$

#### **Quadratic Mountain Stable Normal Form**

For large enough B system is stable and  $\exists$  a coordinate change, a canonical transformation  $(q, p) \rightarrow (Q, P)$ , to

$$H = \frac{|\omega_f|}{2} \left( P_f^2 + Q_f^2 \right) - \frac{|\omega_s|}{2} \left( P_s^2 + Q_s^2 \right)$$

Slow mode is a <u>negative energy mode</u> – a stable oscillation that lowers the energy relative to the equilibrium state.

Weierstrass (1894), Williamson (1936), ...

• Hamiltonian normal form theory.

•

#### **Krein-Moser Bifurcation Theorem**

Krein (1950) – Moser (1958) – Sturrock (1958)

Such bifurcation to instability (with quartets) can only happen if colliding eigenvalues have opposite signature  $\sigma_i \in \{\pm\}$ , where

$$H = \sum_{i} \sigma_i |\omega_i| (p_i^2 + q_i^2)/2 = \sum_{i} \sigma_i |\omega_i| J_i$$

One must be a negative energy mode.

Sturrock looked at two-stream instability.

# **Vlasov in Class of Hamiltonian Field Theories**

- plasma physics (charged particles-electrostatic)
- vortex dynamics, QG, shear flow
- stellar dynamics
- statistical physics (XY-interaction)
- ...
- general transport via mean field theory

## Hamiltonian Structure

Noncanonical Poisson Bracket:

$$\{F,G\} = \int_{\mathcal{Z}} dqdp f\left[\frac{\delta F}{\delta f}, \frac{\delta G}{\delta f}\right] = \int_{\mathcal{Z}} dqdp F_f \mathcal{J}G_f = \left\langle f, [F_f, G_f] \right\rangle$$

Cosymplectic Operator:

$$\mathcal{J} \cdot = \frac{\partial f}{\partial p} \frac{\partial}{\partial q} - \frac{\partial f}{\partial q} \frac{\partial}{\partial p}$$

Vlasov:

$$\frac{\partial f}{\partial t} = \{f, H\} = \mathcal{J}\frac{\delta H}{\delta f} = -[f, \mathcal{E}].$$

Casimir Degeneracy:

$$\{C, F\} = 0$$
  $\forall F$  for  $C[f] = \int_{\mathcal{Z}} dq dp C(f)$ 

Too many variables and not canonical. See Cartoon – Hamiltonian on leaf.

## **VP** Cartoon– Symplectic Rearrangement

$$f(x, v, t) = \tilde{f} \circ \tilde{z}$$
$$f \sim g \text{ if } f = g \circ z$$

with z symplectomorphism





p = mv

 $\mu$  volume measure

$$f(x,v,t) = \mathring{f}(\mathring{x}(x,v,t),\mathring{v}(x,v,t))$$

## **Linear Hamiltonian Theory**

Expand *f*-dependent Poisson bracket and Hamiltonian  $\Rightarrow$ 

Linear Poisson Bracket:

$$\{F,G\}_L = \int f_0 \left[\frac{\delta F}{\delta \delta f}, \frac{\delta G}{\delta \delta f}\right] dx dv ,$$
  
$$\frac{\partial \delta f}{\partial \delta f} = \left(\int f_0 \left[\frac{\delta F}{\delta \delta f}, \frac{\delta G}{\delta \delta f}\right] dx dv ,$$

$$\frac{\partial \delta f}{\partial t} = \{\delta f, H_L\}_L,\,$$

where quadratic Hamiltonian  $H_L$  is the Kruskal-Oberman energy and linear Poisson bracket is  $\{, \}_L = \{, \}_{f_0}$ .

Note:

 $\frac{\delta f \text{ not canonical}}{H_L \text{ not diagonal}}$ 



# Landau's Problem Again

Assume

$$\delta f = \sum_{k} f_k(v,t) e^{ikx}, \qquad \delta \phi = \sum_{k} \phi_k(t) e^{ikx}$$

Linearized EOM:

$$\frac{\partial f_k}{\partial t} + ikvf_k + ik\phi_k \frac{e}{m} \frac{\partial f_0}{\partial v} = 0, \qquad k^2 \phi_k = -4\pi e \int_{\mathbb{R}} f_k(v,t) \, dv$$

## **Canonization & Diagonalization**

Fourier Linear Poisson Bracket:

$$\{F,G\}_L = \sum_{k=1}^{\infty} \frac{ik}{m} \int_{\mathbb{R}} f'_0 \left( \frac{\delta F}{\delta f_k} \frac{\delta G}{\delta f_{-k}} - \frac{\delta G}{\delta f_k} \frac{\delta F}{\delta f_{-k}} \right) dv$$

Linear Hamiltonian:

$$H_{L} = -\frac{m}{2} \sum_{k} \int_{\mathbb{R}} \frac{v}{f_{0}'} |f_{k}|^{2} dv + \frac{1}{8\pi} \sum_{k} k^{2} |\phi_{k}|^{2}$$
$$= \sum_{k,k'} \int_{\mathbb{R}} \int_{\mathbb{R}} f_{k}(v) \mathcal{O}_{k,k'}(v|v') f_{k'}(v') dv dv'$$

Canonization:

$$q_k(v,t) = f_k(v,t), \qquad p_k(v,t) = \frac{m}{ikf'_0}f_{-k}(v,t) \implies$$

$$\{F,G\}_L = \sum_{k=1}^{\infty} \int_{\mathbb{R}} \left( \frac{\delta F}{\delta q_k} \frac{\delta G}{\delta p_k} - \frac{\delta G}{\delta q_k} \frac{\delta F}{\delta p_k} \right) dv$$

# Diagonalization

Mixed Variable Generating Functional:

$$\mathcal{F}[q, P'] = \sum_{k=1}^{\infty} \int_{\mathbb{R}} q_k(v) G[P'_k](v) dv$$

Canonical Coordinate Change  $(q, p) \leftrightarrow (Q', P')$ :

New Hamiltonian:

$$H_L = \frac{1}{2} \sum_{k=1}^{\infty} \int_{\mathbb{R}} du \,\sigma_k(u) \omega_k(u) \left[ Q_k^2(u) + P_k^2(u) \right]$$
  
$$= \sum_{k=1}^{\infty} \int_{\mathbb{R}} d\omega \,\omega \,\frac{|\epsilon(k,\omega)|^2}{\epsilon_I(k,\omega)} \,|E_k(\omega)|^2 = \sum_{k=1}^{\infty} \int_{\mathbb{R}} d\omega \,\omega \,J_k(\omega)$$

where  $\omega_k(u) = |ku|$  and the signature is

 $\sigma_k(v) := -\operatorname{sgn}(vf'_0(v))$ 

Note: wave energy (Von Laue 1905)  $\sim |E_k(\omega)|^2 \omega \partial \epsilon / \partial \omega$  has no meaning/use for stable Vlasov continuous spectrum.

• Continuum Hamiltonian Hopf Bifurcation

# Main CHH Results

- Let  $f_0$  be a stable equilibrium solution of the Vlasov-Poisson equation.
- If  $f'_0 = 0$  has more than one solution there exist infinitesimal dynamically accessible perturbations that make the system unstable.
- The frequency of the unstable modes is in a neighborhood of the solutions of  $f'_0$  that have  $f''_0 > 0$ .
- If there is only one solution to  $f'_0 = 0$ , then the system is structurally stable.
- If dynamical accessibility is not required then  $f'_0$  is always structurally unstable.

# **Structurally Unstable Equilibrium**



← Pertrubed Maxwellian

Dynamically accessible perturbations are physical perturbations since they result from electric fields.

# **Destabilization of Maxwellian Distribution**



#### Hamiltonian Spectrum

Hamiltonian Operator:

$$f_{kt} = -ikvf_k + \frac{if_0'}{k} \int_{\mathbb{R}} d\bar{v} f_k(\bar{v}, t) =: T_k f_k,$$

Complete System:

 $f_{kt} = T_k f_k$  and  $f_{-kt} = T_{-k} f_{-k}$ ,  $k \in \mathbb{R}^+$ 

**Lemma** If  $\lambda$  is an eigenvalue of the Vlasov equation linearized about the equilibrium  $f'_0(v)$ , then so are  $-\lambda$  and  $\lambda^*$ . Thus if  $\lambda = \gamma + i\omega$ , then eigenvalues occur in the pairs,  $\pm \gamma$  and  $\pm i\omega$ , for purely real and imaginary cases, respectively, or quartets,  $\lambda = \pm \gamma \pm i\omega$ , for complex eigenvalues.

#### **Spectral Stability**

**Definition** The dynamics of a Hamiltonian system linearized around some equilibrium solution, with the phase space of solutions in some Banach space  $\mathcal{B}$ , is <u>spectrally stable</u> if the spectrum  $\sigma(T)$  of the time evolution operator T is purely imaginary.

**Theorem** If for some  $k \in \mathbb{R}^+$  and  $u = \omega/k$  in the upper half plane the plasma dispersion relation,

$$\varepsilon(k,u) := 1 - k^{-2} \int_{\mathbb{R}} dv \frac{f'_0}{u-v} = 0,$$

then the system with equilibrium  $f_0$  is spectrally unstable. Otherwise it is spectrally stable.

## **Nyquist Method**

$$f'_0 \in C^{0,\alpha}(\mathbb{R}) \Rightarrow \varepsilon \in C^{\omega}(uhp).$$

Therefore, Argument Principle  $\Rightarrow$  winding # = # zeros of  $\varepsilon$ 



#### **Spectral Theorem**

Set k = 1 and consider  $T: f \mapsto ivf - if'_0 \int f$  in the space  $W^{1,1}(\mathbb{R})$ .

 $W^{1,1}(\mathbb{R})$  is Sobolev space containing closure of functions

$$||f||_{1,1} = ||f||_1 + ||f'||_1 = \int_{\mathbb{R}} dv(|f| + |f'|)$$

**Definition** Resolvent of T is  $R(T,\lambda) = (T - \lambda I)^{-1}$  and  $\lambda \in \sigma(T)$ . (i)  $\lambda$  in point spectrum,  $\sigma_p(T)$ , if  $R(T,\lambda)$  not injective. (ii)  $\lambda$  in residual spectrum,  $\sigma_r(T)$ , if  $R(T,\lambda)$  exists but not densely defined. (iii)  $\lambda$  in continuous spectrum,  $\sigma_c(T)$ , if  $R(T,\lambda)$  exists, densely defined but not bounded.

**Theorem** Let  $\lambda = iu$ . (i)  $\sigma_p(T)$  consists of all points  $iu \in \mathbb{C}$ , where  $\varepsilon = 1 - k^{-2} \int_{\mathbb{R}} dv f'_0/(u-v) = 0$ . (ii)  $\sigma_c(T)$  consists of all  $\lambda = iu$  with  $u \in \mathbb{R} \setminus (-i\sigma_p(T) \cap \mathbb{R})$ . (iii)  $\sigma_r(T)$  contains all the points  $\lambda = iu$  in the complement of  $\sigma_p(T) \cup \sigma_c(T)$  that satisfy  $f'_0(u) = 0$ .

cf. e.g. P. Degond (1986). Similar but different.

# The CHH Bifurcation

- Usual case:  $f_0(v, v_d)$  one-parameter family of equilibria. Vary  $v_d$ , embedded mode appears in continuous spectrum, then  $\varepsilon(k, \omega)$  has a root in uhp.
- But all equilibria infinitesmally close to instability in  $L^p(\mathbb{R})$ . Need measure of distance to bifurcation.
- Waterbag 'onion' replacement for  $f_0$  has ordinary Hamiltonian Hopf bifurcation. Thus, gives a discretization of the continuous spectrum.

# • Nonlinear Normal Forms

#### **Single-Wave Behavior- Nonlinear**

Behavior near marginality in many simulations in various physical contexts



### **Single-Wave Model**

Asymptotics with trapping scaling ...  $\Rightarrow$ 

$$Q_t + [Q, \mathcal{E}] = 0, \qquad \mathcal{E} = y^2/2 - \varphi$$
$$iA_t = \left\langle Q e^{-ix} \right\rangle, \qquad \varphi = A e^{ix} + A^* e^{-ix},$$

where

$$[f,g] := f_x g_y - f_y g_x, \qquad \langle \cdot \rangle := \frac{1}{2\pi} \int_{-\infty}^{\infty} dy \int_{0}^{2\pi} dx \quad (1)$$

and

 $Q(x, y, t) = \text{density (vorticity)}, \quad \varphi(x, t) = \text{potential (streamfunc-tion)}, A(t) = \text{single-wave of amplitude}, \quad \mathcal{E} = \text{particle energy}$ 

Model has continuous spectrum with embedded mode that can be pushed into instability and then tracked nonlinearly.

# **Summary**

**Underview:** 

- Integral Transform and Inverse Problem
- Energy and Signature
- Continuum Hamiltonian Hopf Bifurcation
- Nonlinear Normal Forms Single Wave Model, Hickernell-Berk-Breizman equation, ...

# Conclusions

- Useful tool akin to Hilbert or other transforms?
- Applicable to wide class of problems. Tailor to problem.
- Motivates further developments (both physics and math)